Lecture 08: RISC-V Single-Cycle Implementation

CSE 564 Computer Architecture Summer 2017

Department of Computer Science and Engineering
Yonghong Yan
yan@oakland.edu
www.secs.oakland.edu/~yan

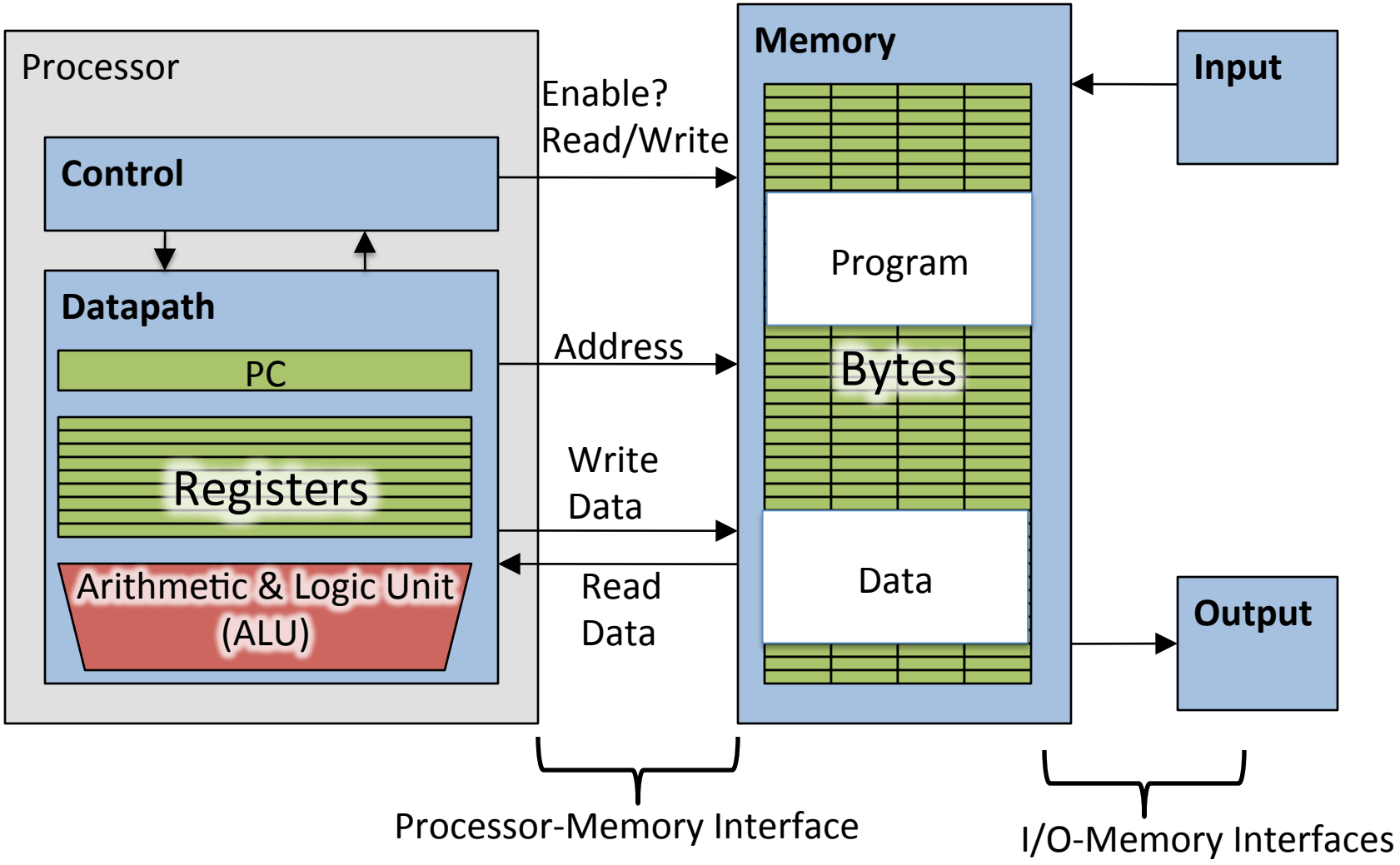
Acknowledgements

- The notes cover Appendix C of the textbook, but we use RISC-V instead of MIPS ISA
  - Slides for general RISC ISA implementation are adapted from Lecture slides for “Computer Organization and Design, Fifth Edition: The Hardware/Software Interface” textbook for general RISC ISA implementation
  - Slides for RISC-V single-cycle implementation are adapted from Computer Science 152: Computer Architecture and Engineering, Spring 2016 by Dr. George Michelogiannakis from UC Berkeley

Introduction

- CPU performance factors $CPU\ \text{Time} = \frac{\text{Instructions}}{\text{Program}} * \frac{\text{Cycles}}{\text{Instruction}} * \frac{\text{Time}}{\text{Cycle}}$
  - Instruction count
    - Determined by ISA and compiler
  - CPI and Cycle time
    - Determined by CPU hardware
- Simple subset, shows most aspects
  - Memory reference: lw, sw
  - Arithmetic/logical: add, sub, and, or, slt
  - Control transfer: beq, j

Components of a Computer

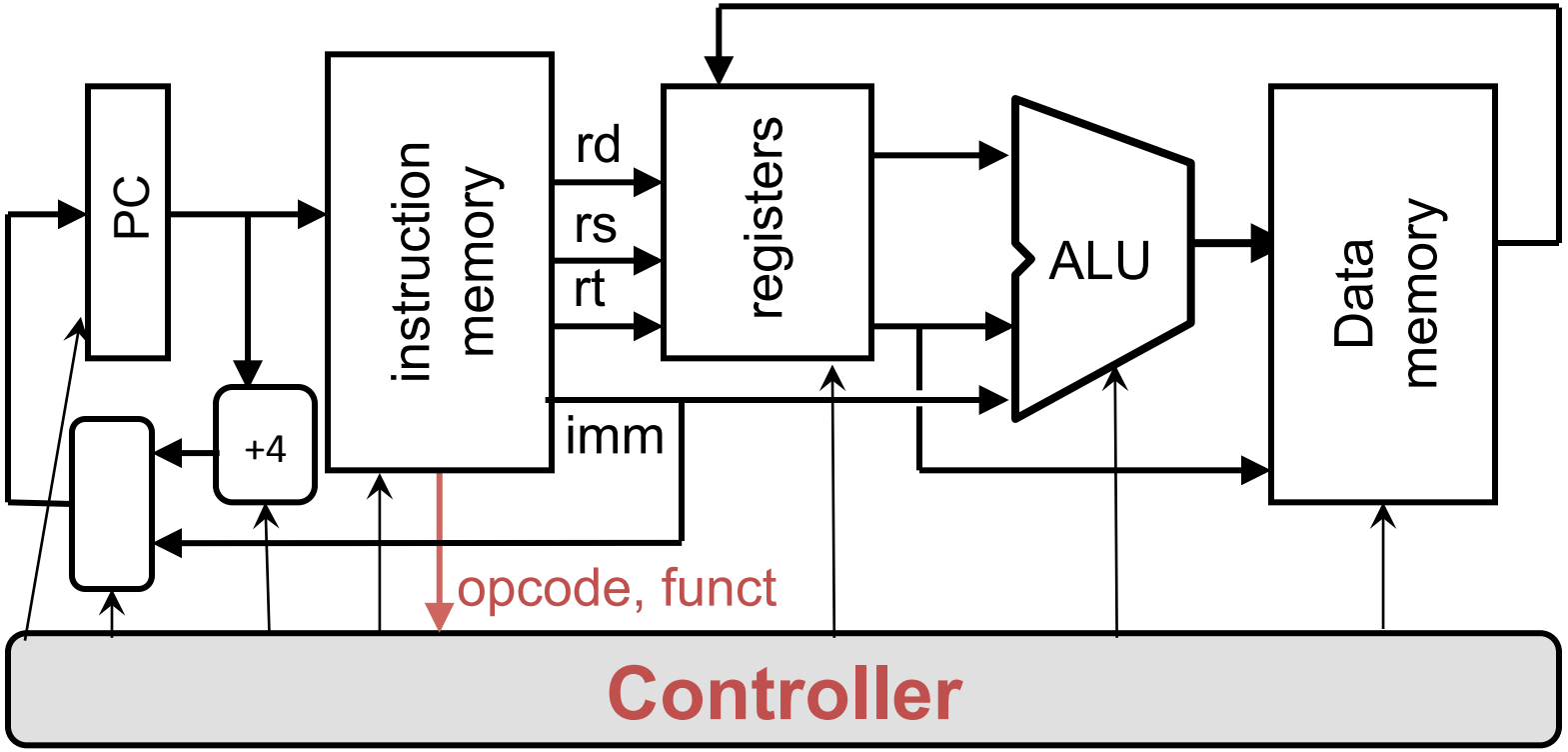


The CPU

- Processor (CPU): the active part of the computer that does all the work (data manipulation and decision-making)
- Datapath: portion of the processor that contains hardware necessary to perform operations required by the processor (the brawn)
- Control : portion of the processor (also in hardware) that tells the datapath what needs to be done (the brain)

Datapath and Control

- Datapath designed to support data transfers required by instructions
- Controller causes correct transfers to happen

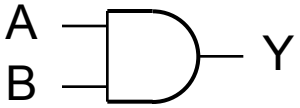


Logic Design Basics

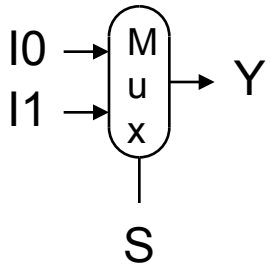
- Information encoded in binary
  - Low voltage = 0, High voltage = 1
  - One wire per bit
  - Multi-bit data encoded on multi-wire buses
- Combinational circuit
  - Operate on data
  - Output is a function of input
- State (sequential) circuit
  - Store information

Combinational Circuits

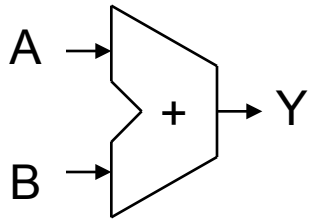
- AND-gate
  - Y = A & B



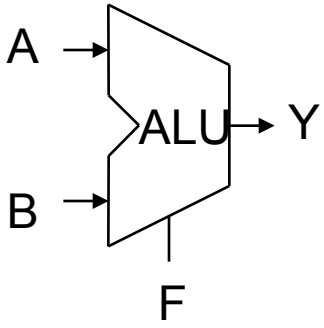
- Multiplexer
  - Y = S ? I1 : I0



- Adder
  - Y = A + B

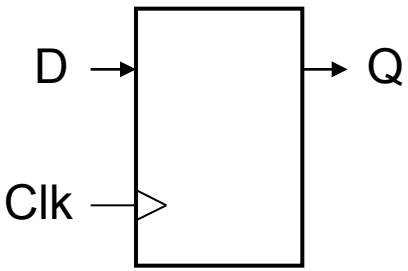


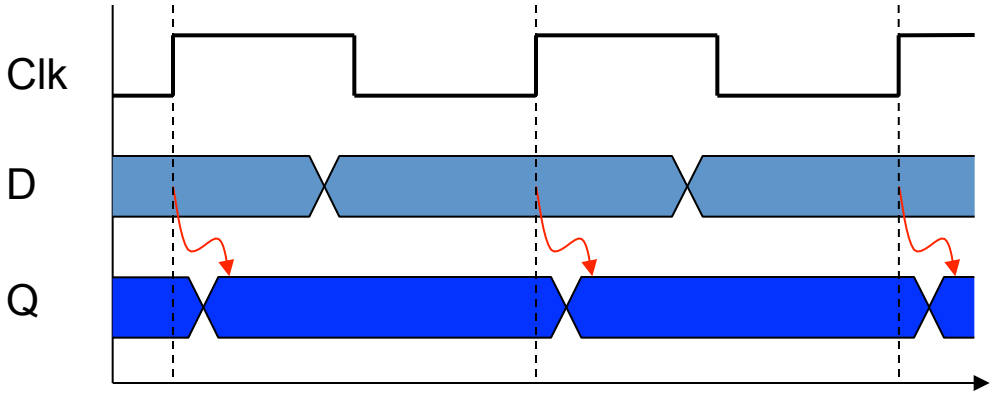
- Arithmetic/Logic Unit
  - Y = F(A, B)



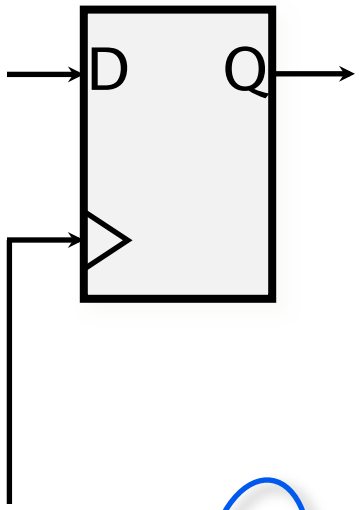
Sequential Circuits

- Register: stores data in a circuit
  - Uses a clock signal to determine when to update the stored value
  - Edge-triggered: update when Clk changes from 0 to 1

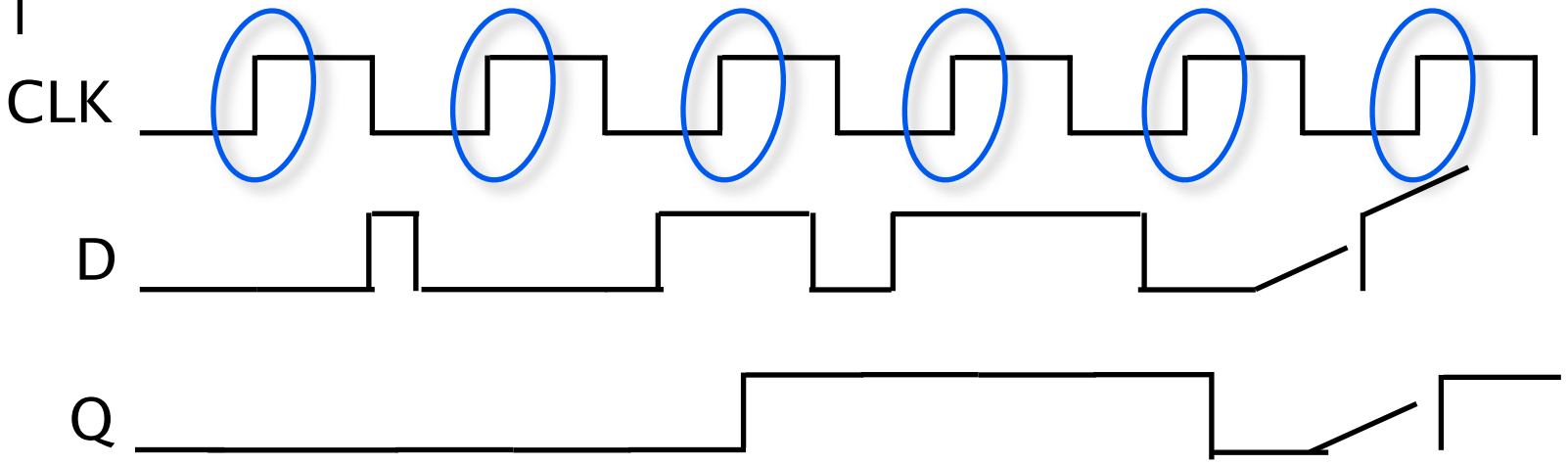




Edge-Triggered D Flip Flops

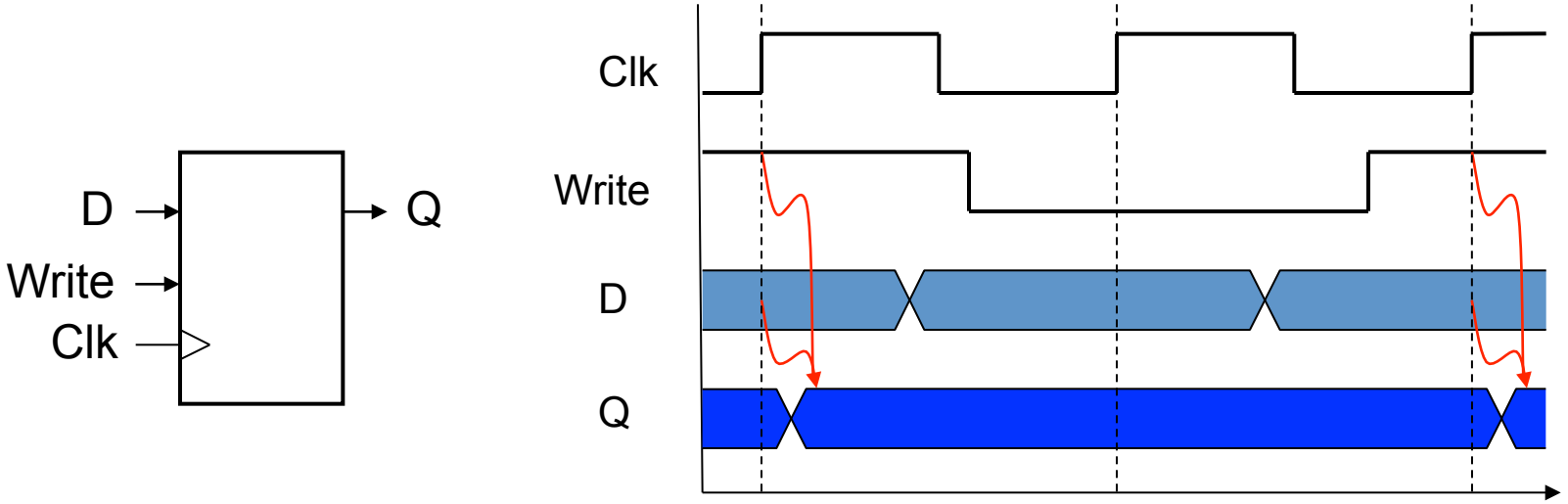


- Value of D is sampled on positive clock edge.
- Q outputs sampled value for rest of cycle.



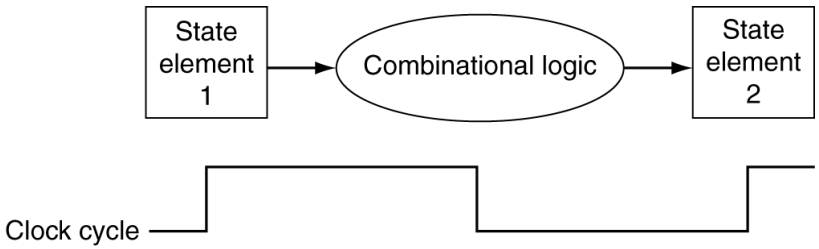
Sequential Circuits

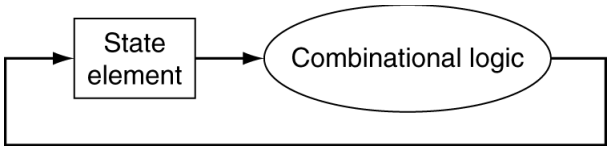
- Register with write control
  - Only updates on clock edge when write control input is 1
  - Used when stored value is required later



Clocking Methodology

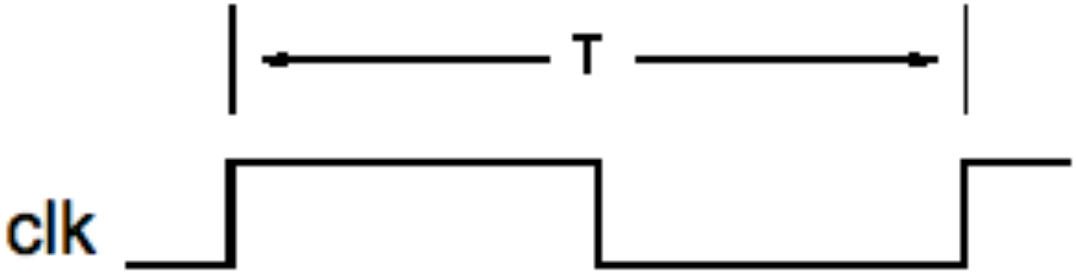
- Combinational logic transforms data during clock cycles
  - Between clock edges
  - Input from state elements, output to state element
  - Longest delay determines clock period





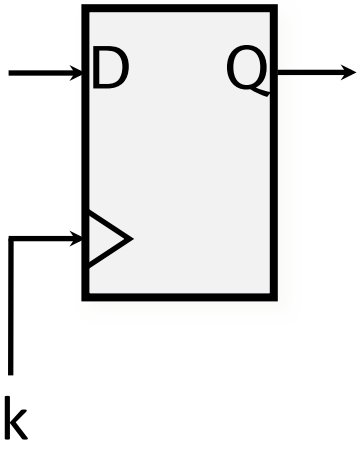
Single cycle data paths

Processor uses synchronous logic design (a "clock").



f	T
1 MHz	1 µs
10 MHz	100 ns
100 MHz	10 ns
1 GHz	1 ns

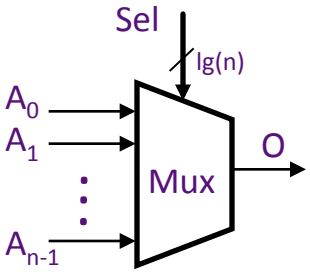
All state elements act like positive edge-triggered flip flops.

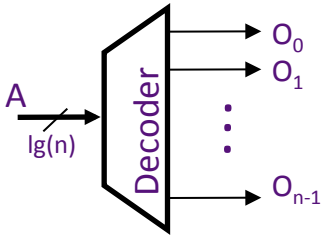


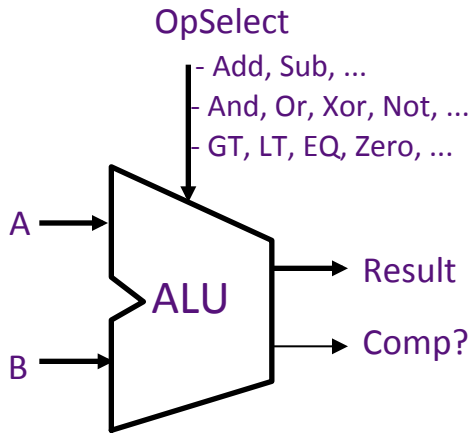
Reset ?

Hardware Elements of CPU

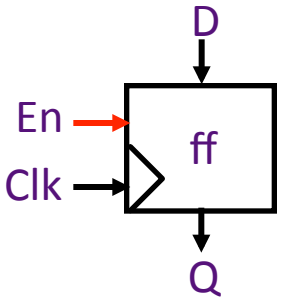
- Combinational circuits
  - Mux, Decoder, ALU, ...

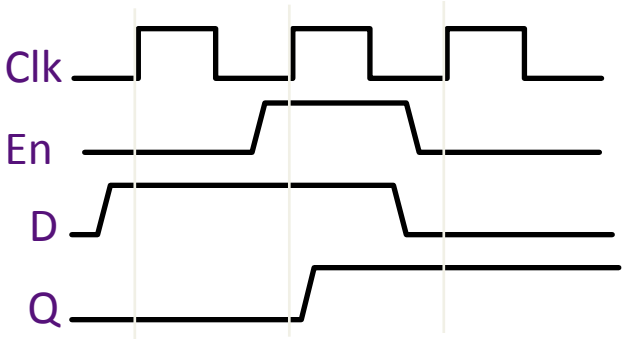






- Synchronous state elements
  - Flipflop, Register, Register file, SRAM, DRAM

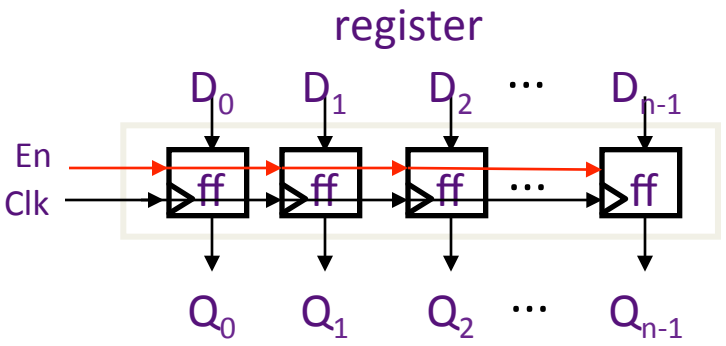


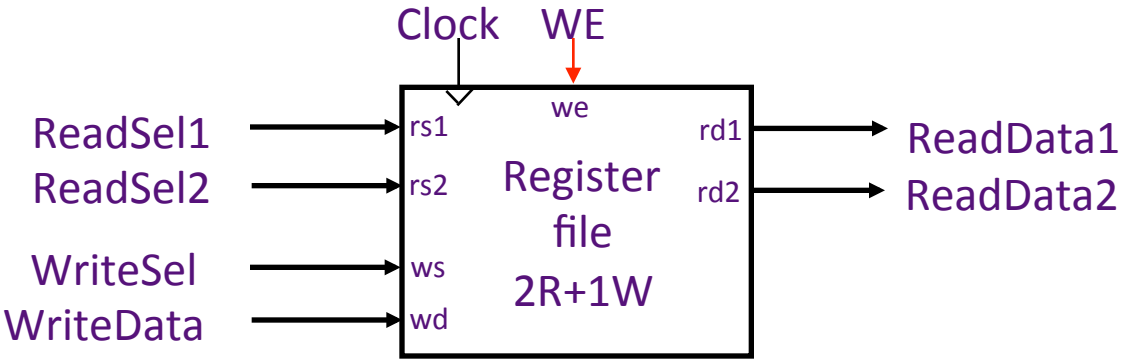


Edge-triggered: Data is sampled at the rising edge

Register Files

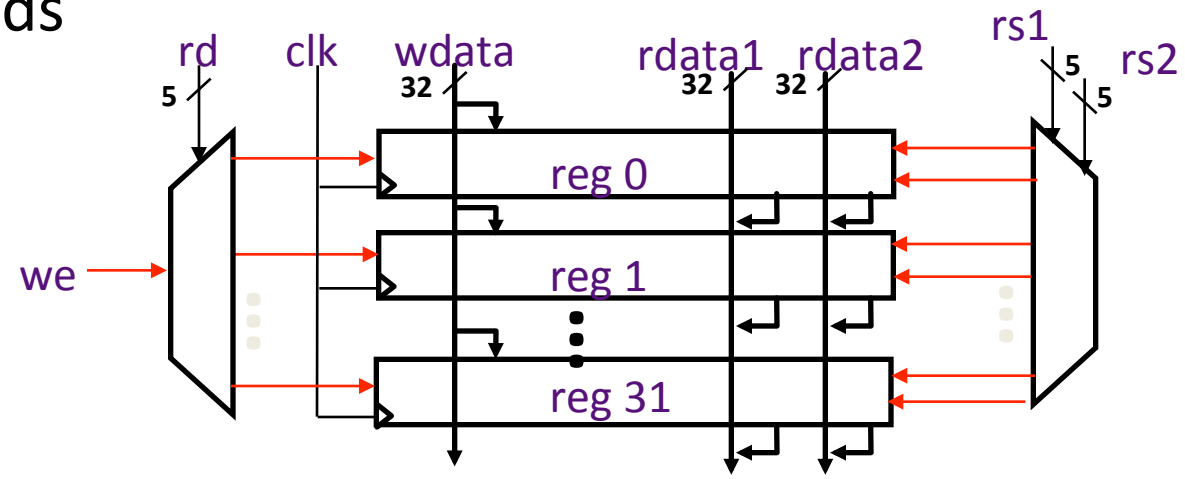
- Reads are combinational



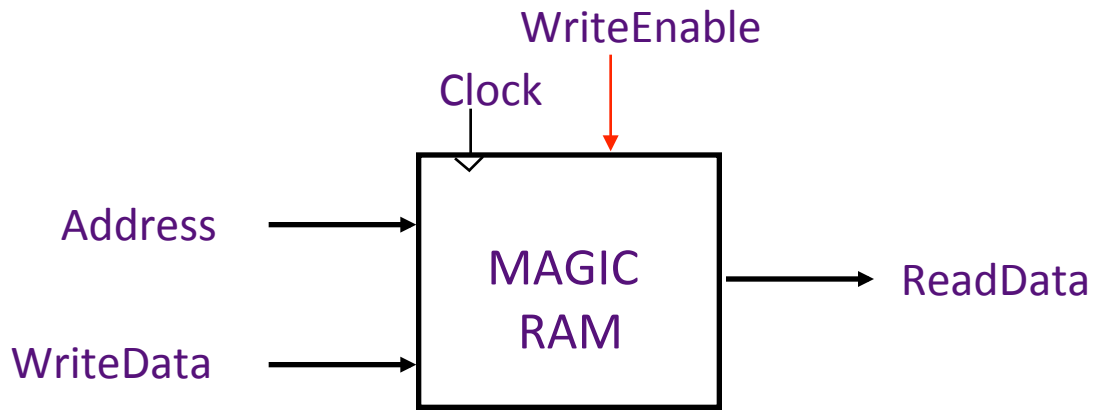


Register File Implementation

- RISC-V integer instructions have at most 2 register source operands



A Simple Memory Model



Reads and writes are always completed in one cycle

- a Read can be done any time (i.e. combinational)
- a Write is performed at the rising clock edge
  if it is enabled

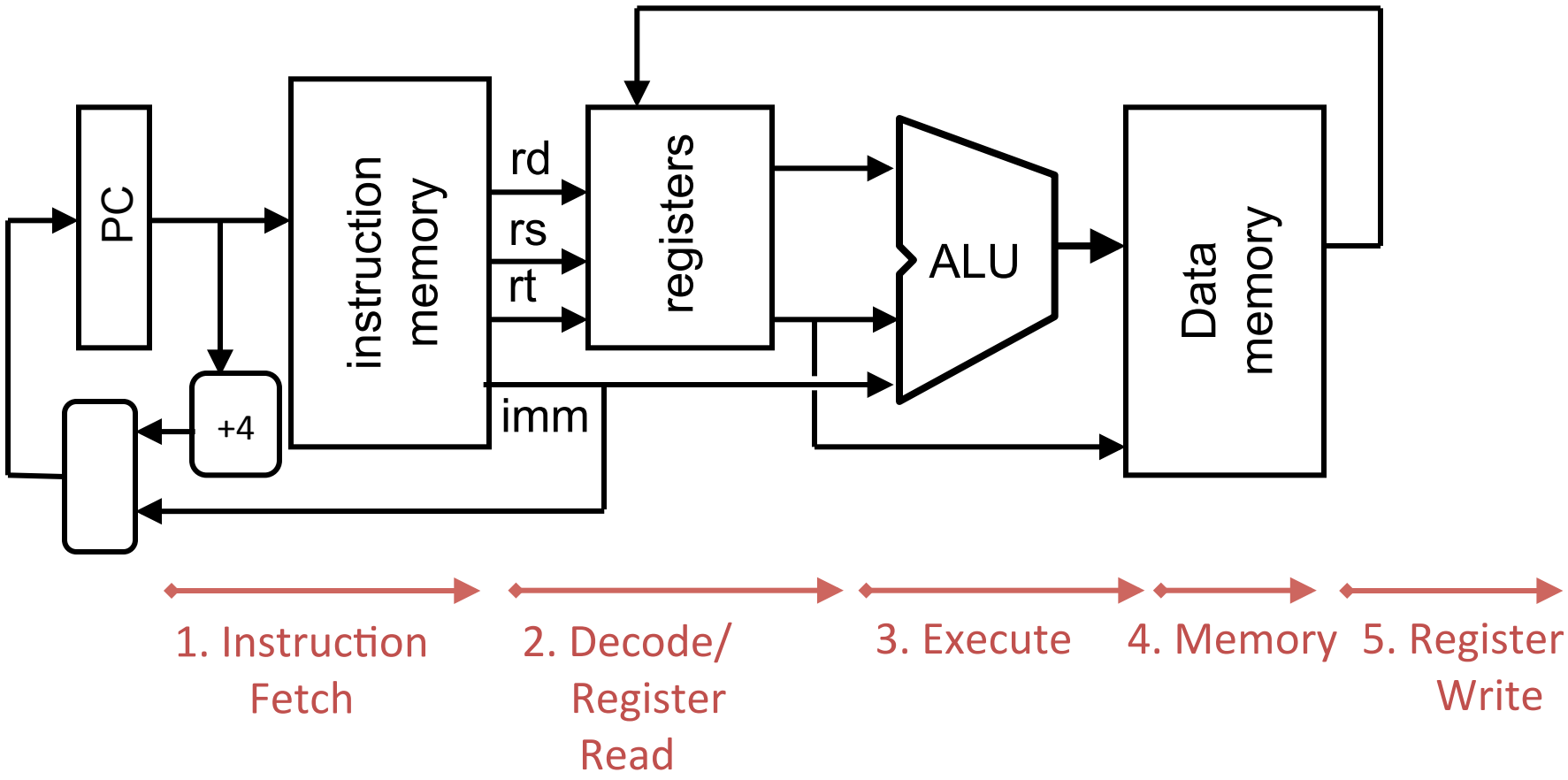
  => *the write address and data*
  must be stable at the clock edge

Later in the course we will present a more realistic model of memory

Five Stages of Instruction Execution

- Stage 1: Instruction Fetch
- Stage 2: Instruction Decode
- Stage 3: ALU (Arithmetic-Logic Unit)
- Stage 4: Memory Access
- Stage 5: Register Write

Stages of Execution on Datapath



Stages of Execution (1/5)

- There is a wide variety of instructions: so what general steps do they have in common?
- Stage 1: Instruction Fetch
  - The 32-bit instruction word must first be fetched from memory
    - the cache-memory hierarchy
  - also, this is where we Increment PC
    - PC = PC + 4, to point to the next instruction: byte addressing so + 4

Stages of Execution (2/5)

- Stage 2: Instruction Decode: gather data from the fields (decode all necessary instruction data)
  1. read the opcode to determine instruction type and field lengths
  2. read in data from all necessary registers
     - for add, read two registers
     - for addi, read one register
     - for jal, no reads necessary

31 25	24 20	19 15	14 12	11 7	6 0
funct7	rs2	rs1	funct3	rd	opcode
7	5	5	3	5	7
0000000	src2	src1	ADD/SLT/SLTU	dest	OP
0000000	src2	src1	AND/OR/XOR	dest	OP
0000000	src2	src1	SLL/SRL	dest	OP
0100000	src2	src1	SUB/SRA	dest	OP

Stages of Execution (3/5)

- Stage 3: ALU (Arithmetic-Logic Unit): the real work of most instructions is done here
  - AL operations:
    - arithmetic (+, -, *, /), shifting, logic (&, |), comparisons (slt)
  - loads and stores
    - lw $t0, 40($t1)
    - the address we are accessing in memory = the value in $t1 PLUS the value 40
    - Addition is done in this stage
  - Conditional branch
    - Comparison is done in this stage (one solution)

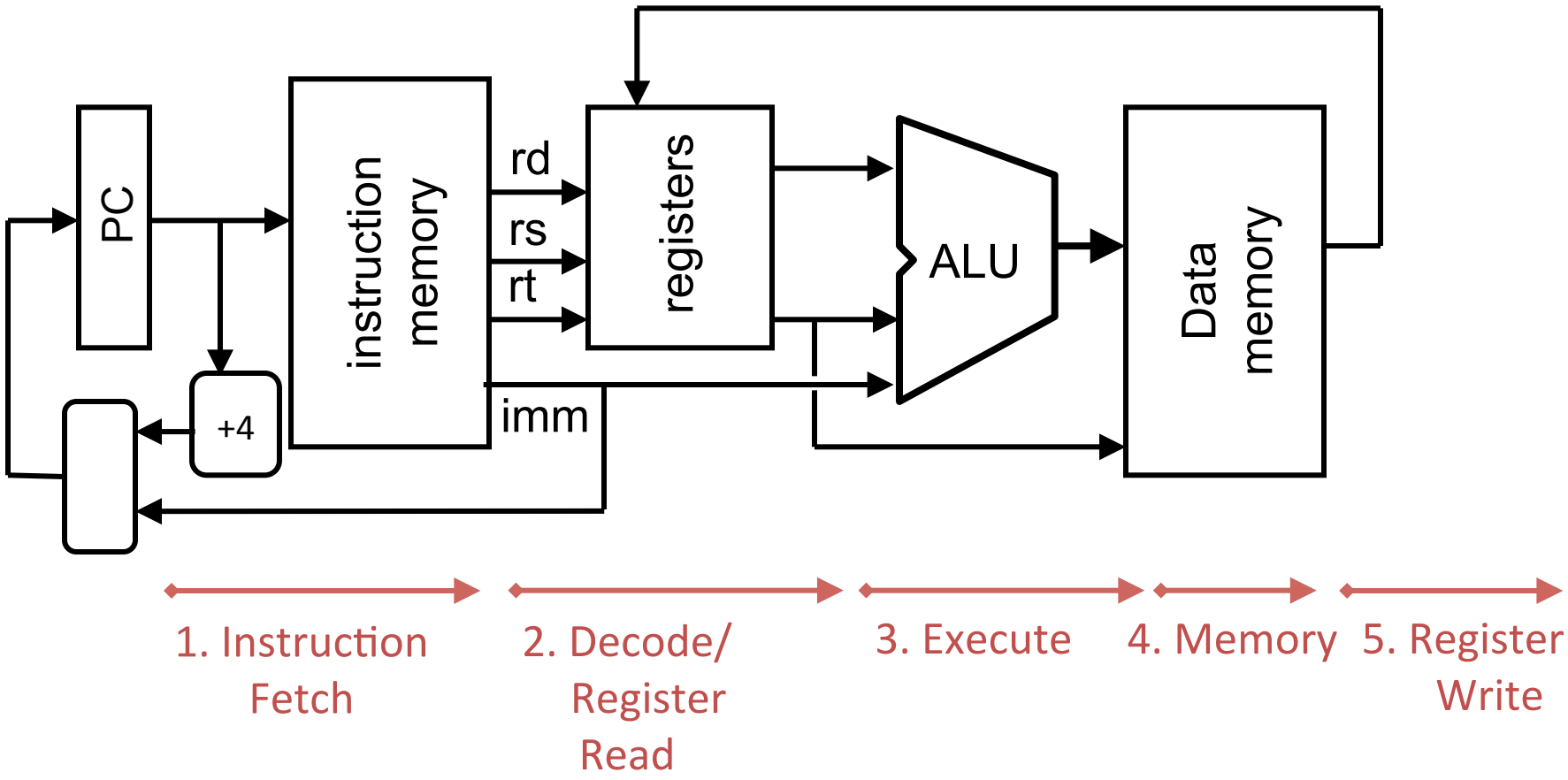
Stages of Execution (4/5)

- Stage 4: Memory Access: only load and store instructions
  - the others remain idle during this stage or skip it all together
  - since these instructions have a unique step, we need this extra stage to account for them
  - as a result of the cache system, this stage is expected to be fast

Stages of Execution (5/5)

- Stage 5: Register Write
  - most instructions write the result of some computation into a register
  - examples: arithmetic, logical, shifts, loads, slt
  - what about stores, branches, jumps?
    - don't write anything into a register at the end
    - these remain idle during this fifth stage or skip it all together

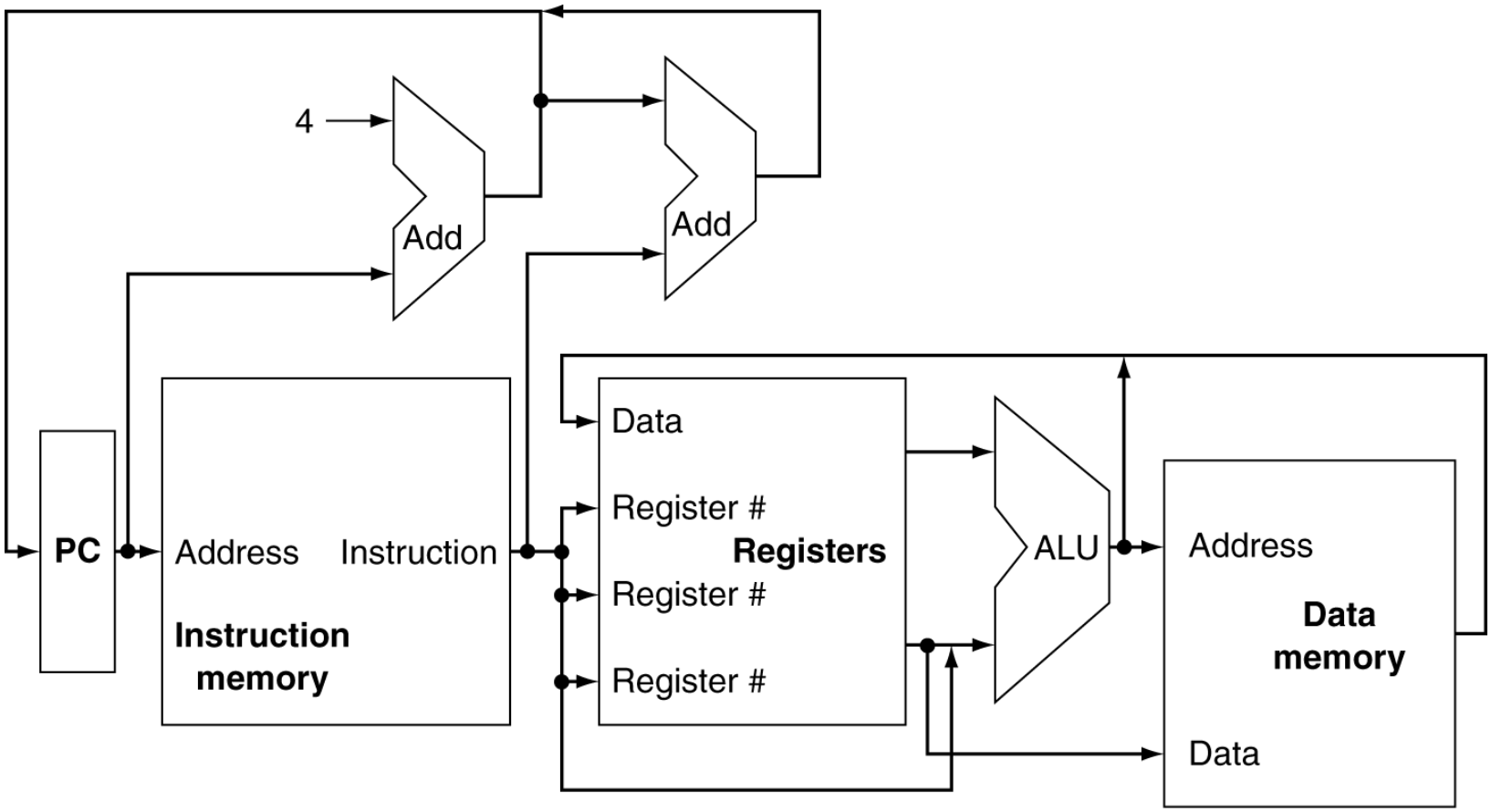
Stages of Execution on Datapath



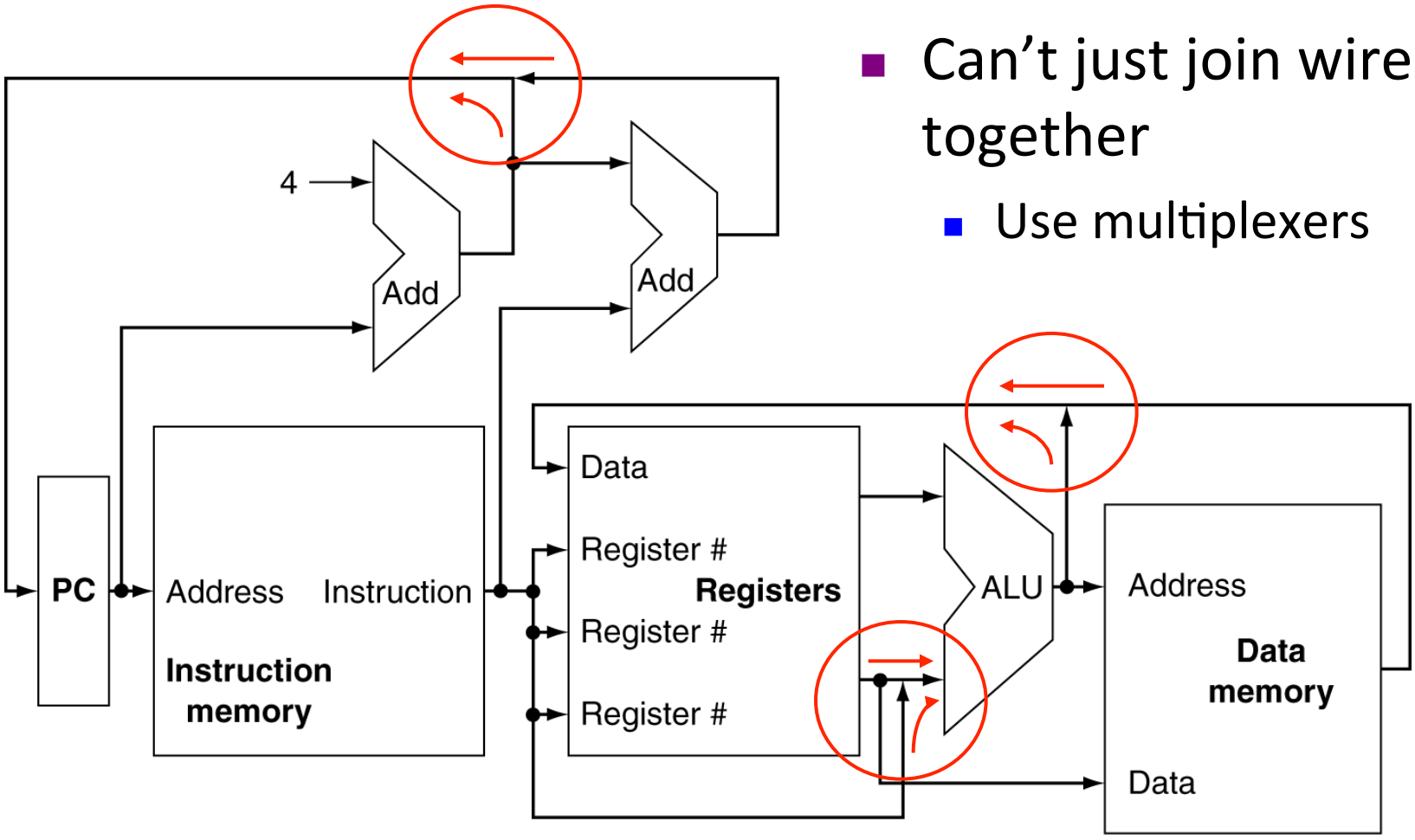
Instruction Execution

- PC → instruction memory, fetch instruction
- Register numbers → register file, read registers
- Depending on instruction class
  - Use ALU to calculate
    - Arithmetic result
    - Memory address for load/store
    - Branch condition and target address
  - Access data memory for load/store
  - PC ← target address or PC + 4

CPU Components

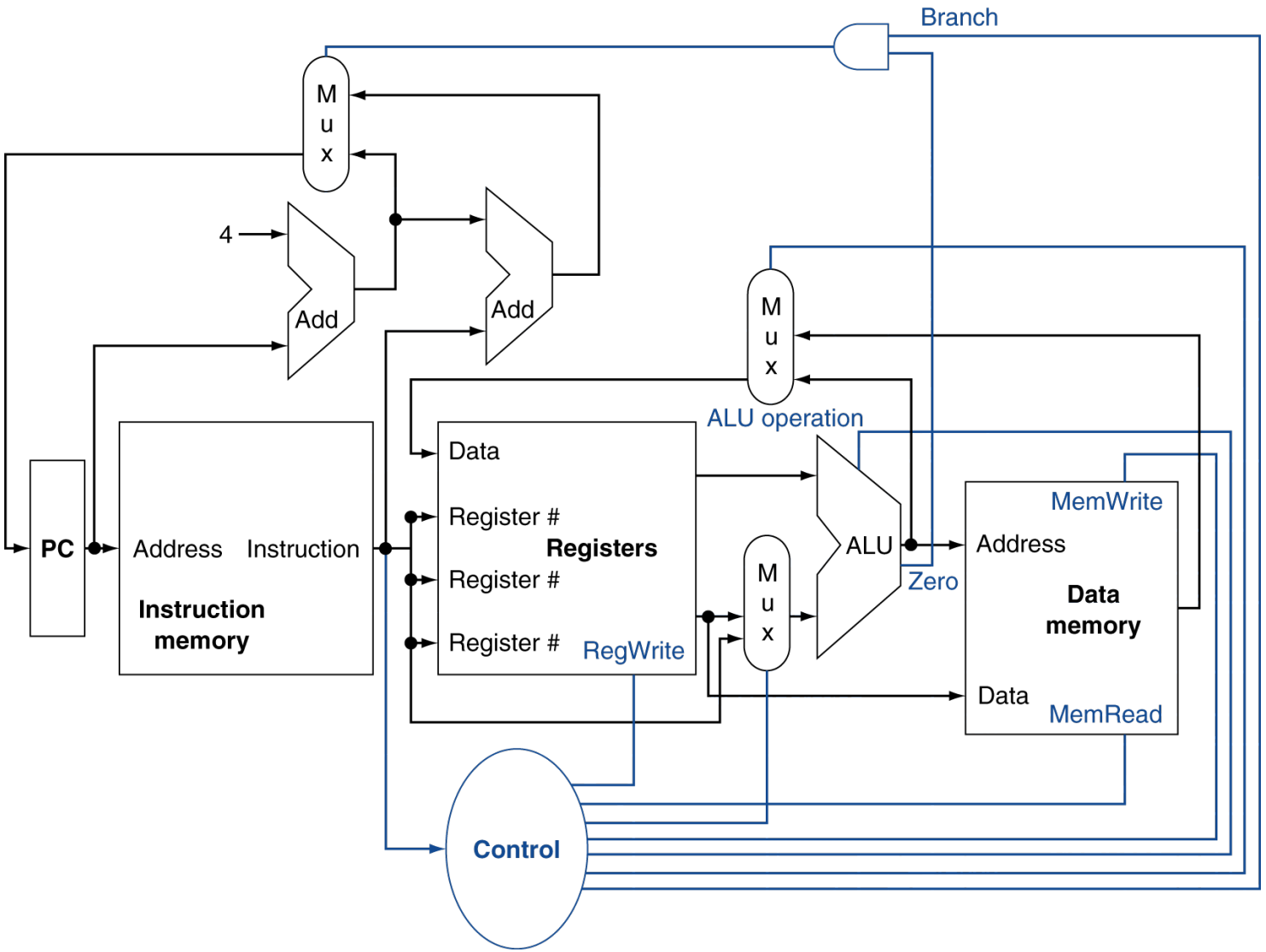


Multiplexers



- Can't just join wires together
  - Use multiplexers

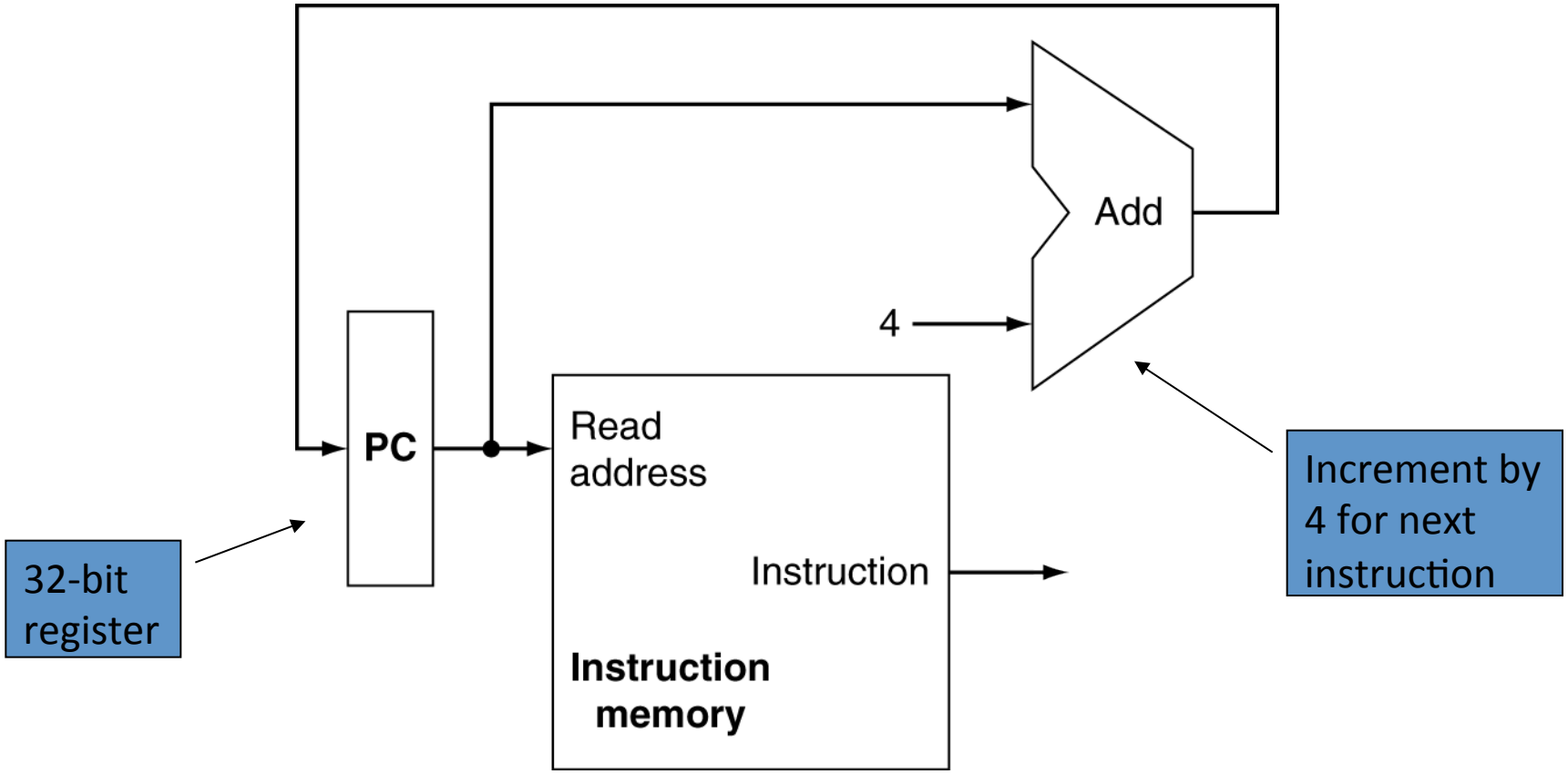
Control Signals



Building a Datapath

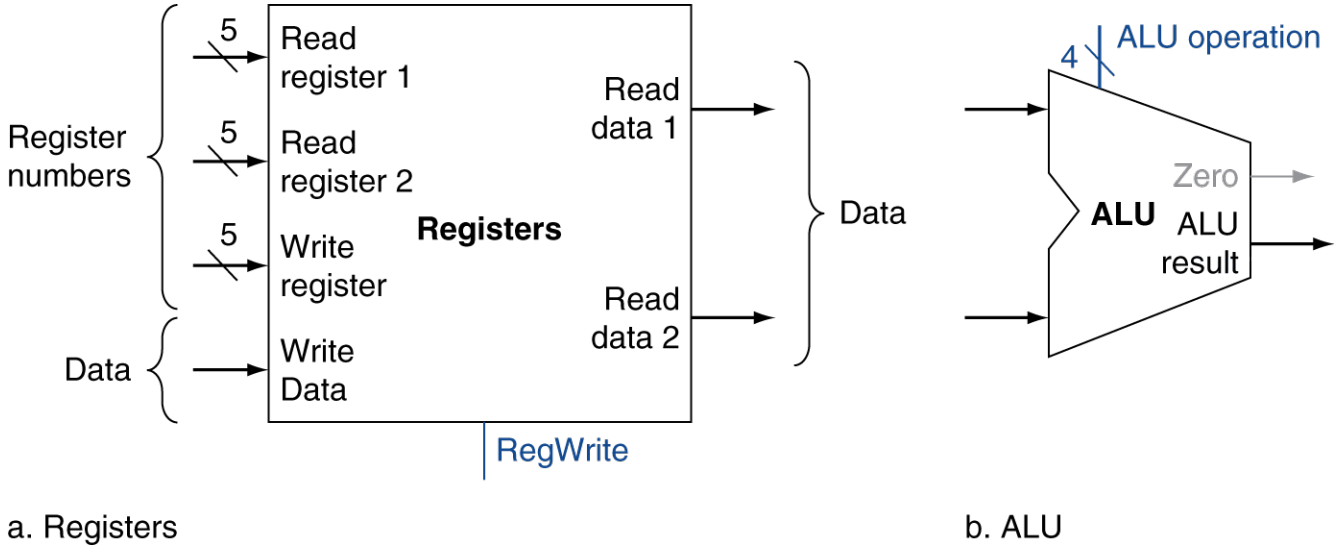
- Datapath
  - Elements that process data and addresses in the CPU
    - Registers, ALUs, mux's, memories, …
- We will build a RISCV datapath incrementally
  - Refining the overview design

Instruction Fetch



R-Format Instructions

- Read two register operands
- Perform arithmetic/logical operation
- Write register result

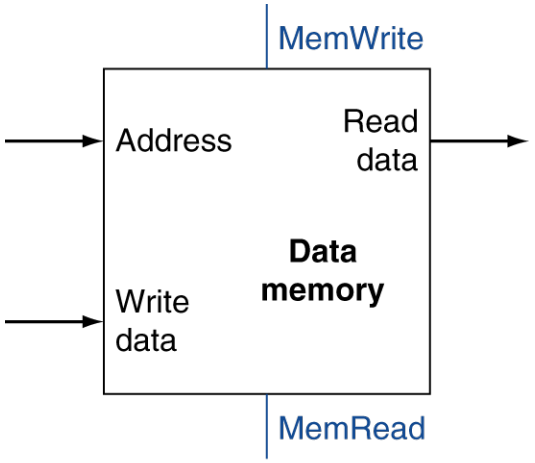


a. Registers

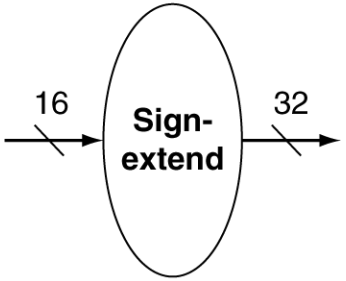
b. ALU

Load/Store Instructions

- Read register operands
- Calculate address using 12-bit offset
  - Use ALU, but sign-extend offset
- Load: Read memory and update register
- Store: Write register value to memory



a. Data memory unit

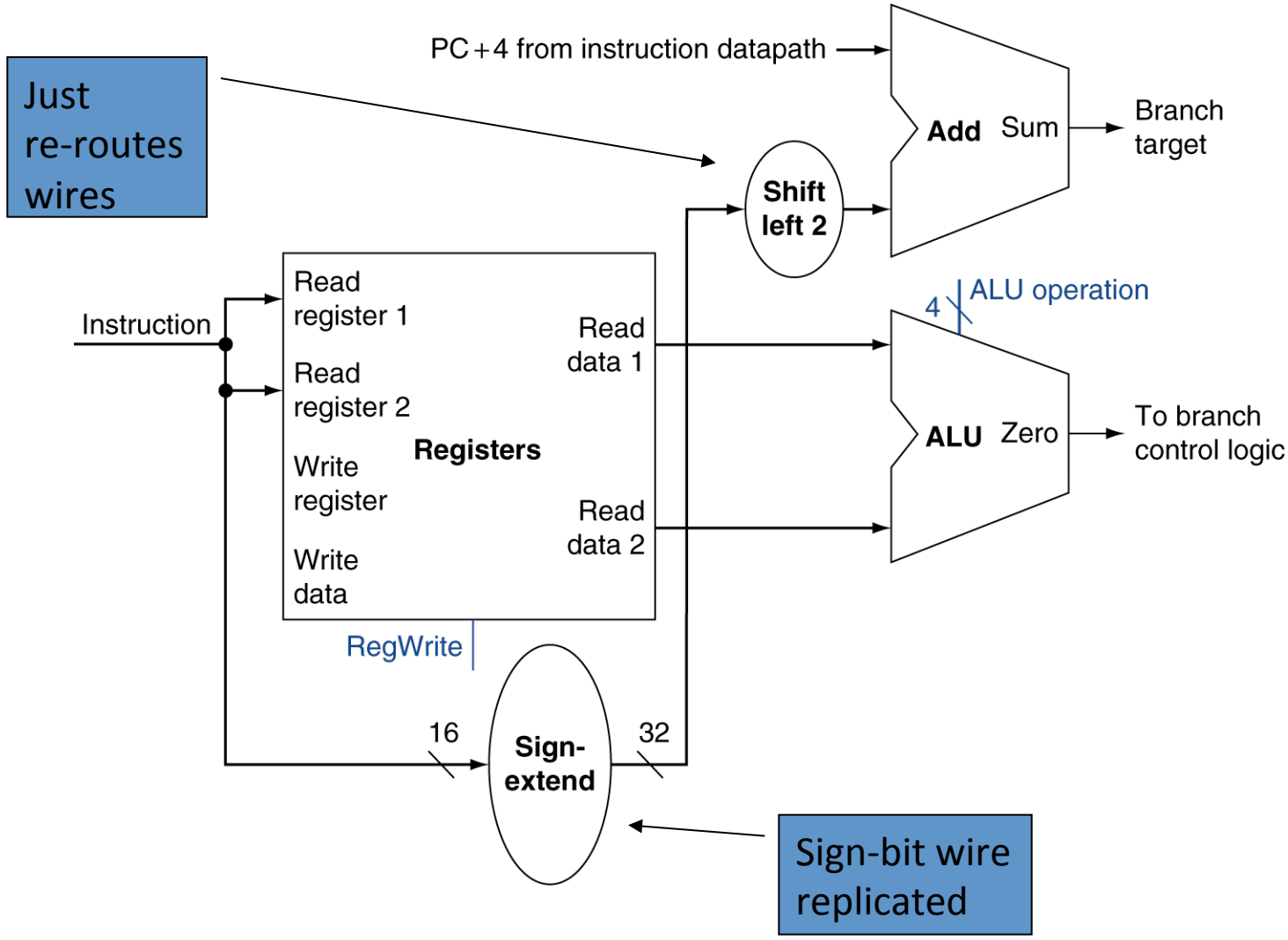


b. Sign extension unit

Branch Instructions

- Read register operands
- **Compare operands**
  - Use ALU, subtract and check Zero output
- **Calculate target address**
  - Sign-extend displacement
  - Shift left 2 places (word displacement)
  - Add to PC + 4
    - Already calculated by instruction fetch

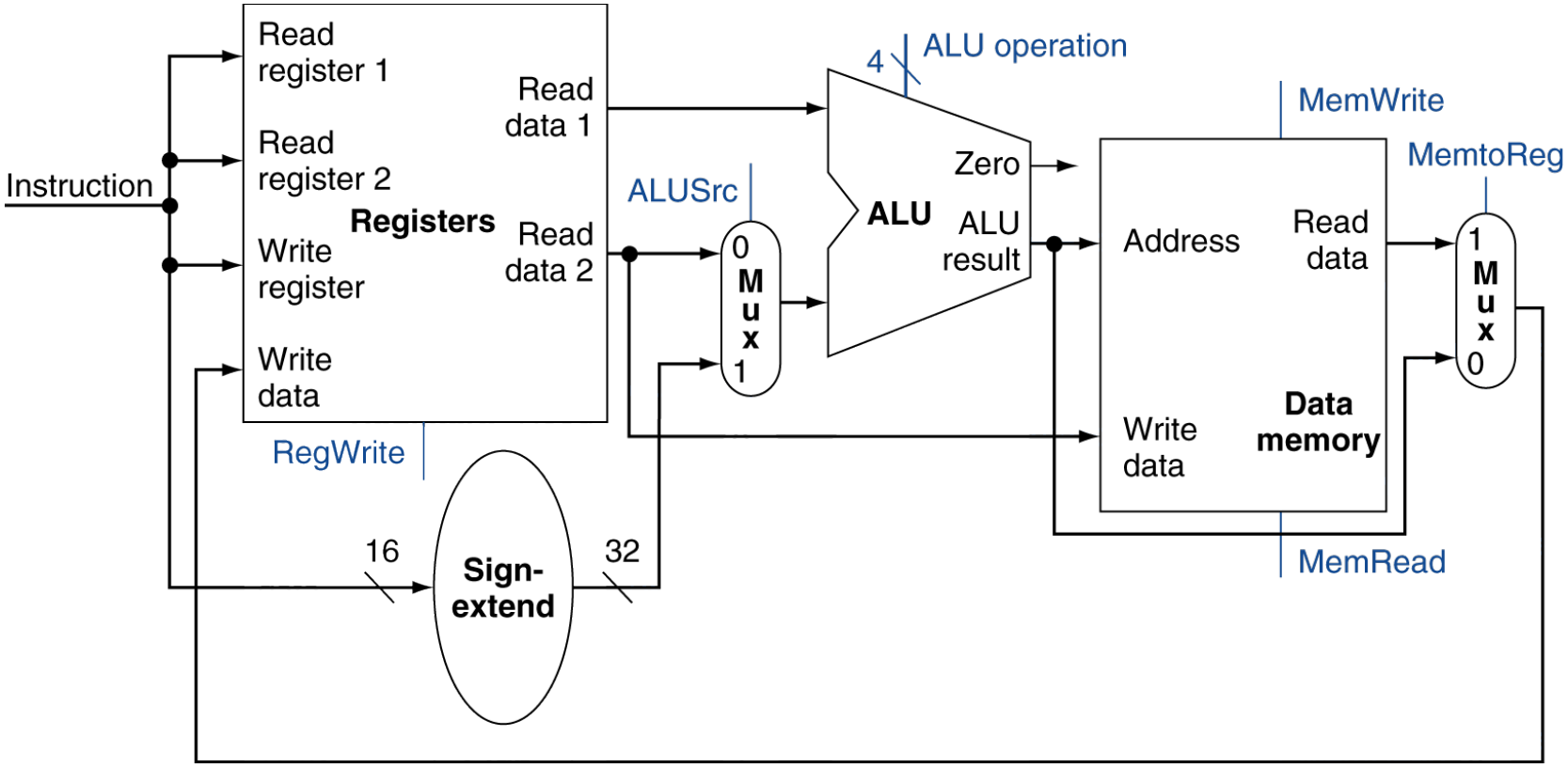
Branch Instructions



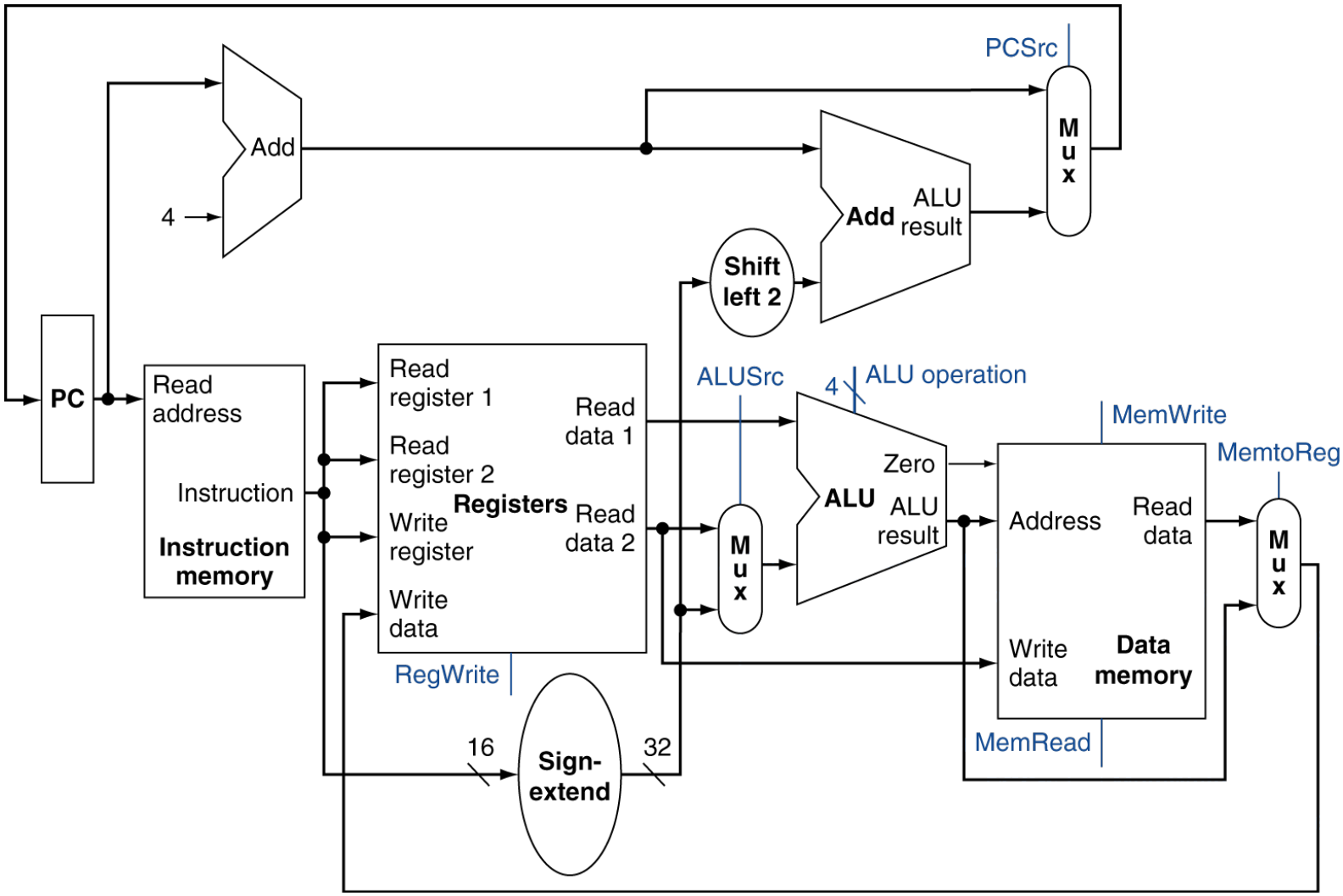
Composing the Elements

- First-cut data path does an instruction in one clock cycle
  - Each datapath element can only do one function at a time
  - Hence, we need separate instruction and data memories
- Use multiplexers where alternate data sources are used for different instructions

R-Type/Load/Store Datapath



Full Datapath



ALU Control

- ALU used for
  - Load/Store: F = add
  - Branch: F = subtract
  - R-type: F depends on funct field

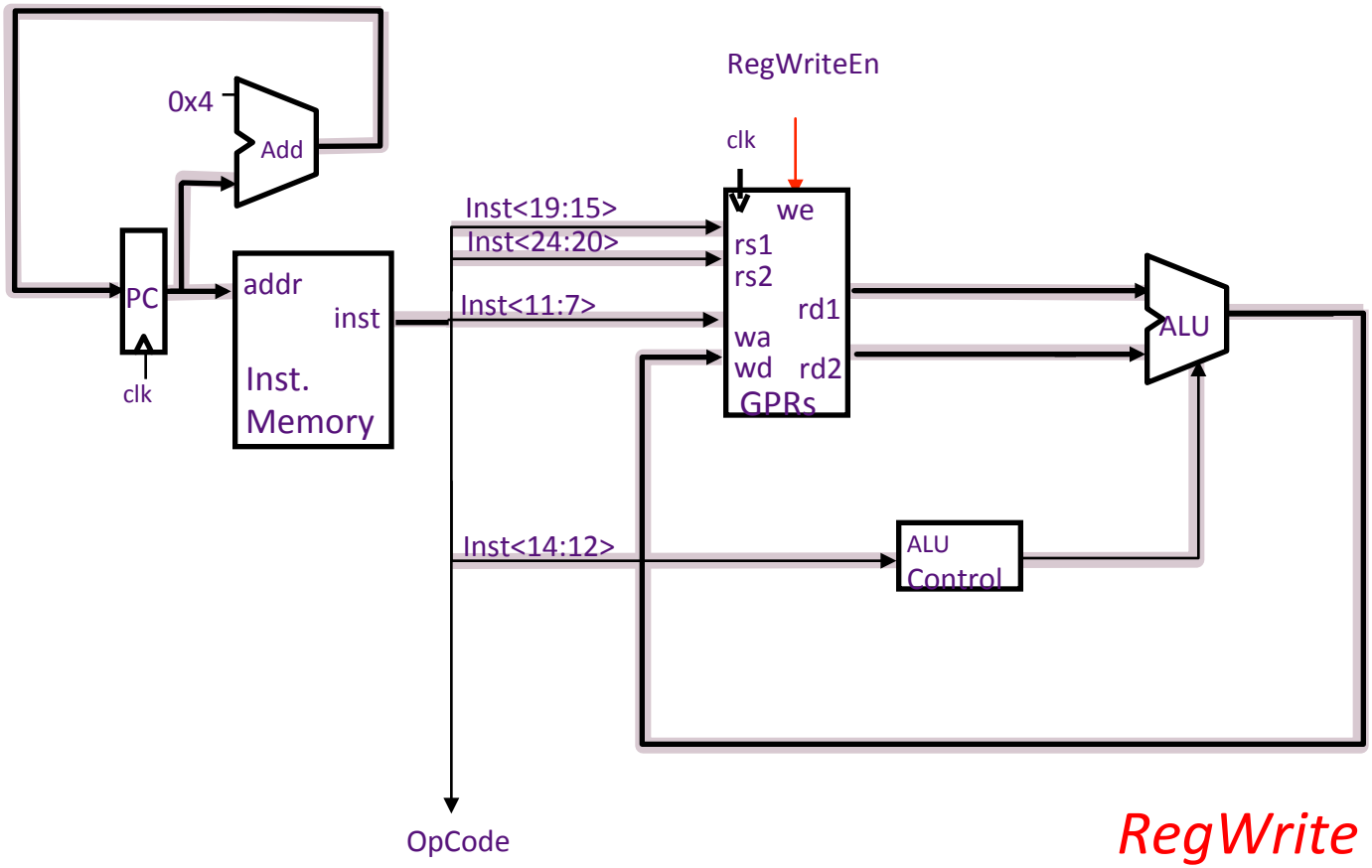
ALU control	Function
0000	AND
0001	OR
0010	add
0110	subtract
0111	set-on-less-than
1100	NOR

ALU Control

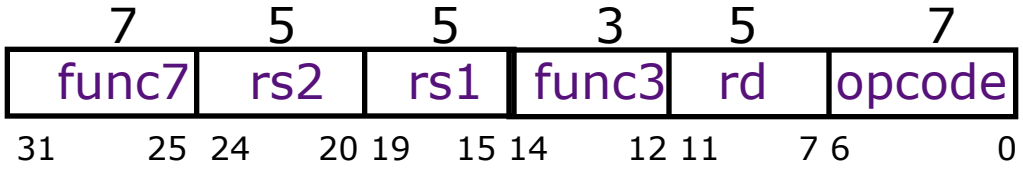
- Assume 2-bit ALUOp derived from opcode
  - Combinational logic derives ALU control

opcode	ALUOp	Operation	funct	ALU function	ALU control
lw	00	load word	XXXXXX	add	0010
sw	00	store word	XXXXXX	add	0010
beq	01	branch equal	XXXXXX	subtract	0110
R-type	10	add	100000	add	0010
		subtract	100010	subtract	0110
		AND	100100	AND	0000
		OR	100101	OR	0001
		set-on-less-than	101010	set-on-less-than	0111

Datapath: Reg-Reg ALU Instructions

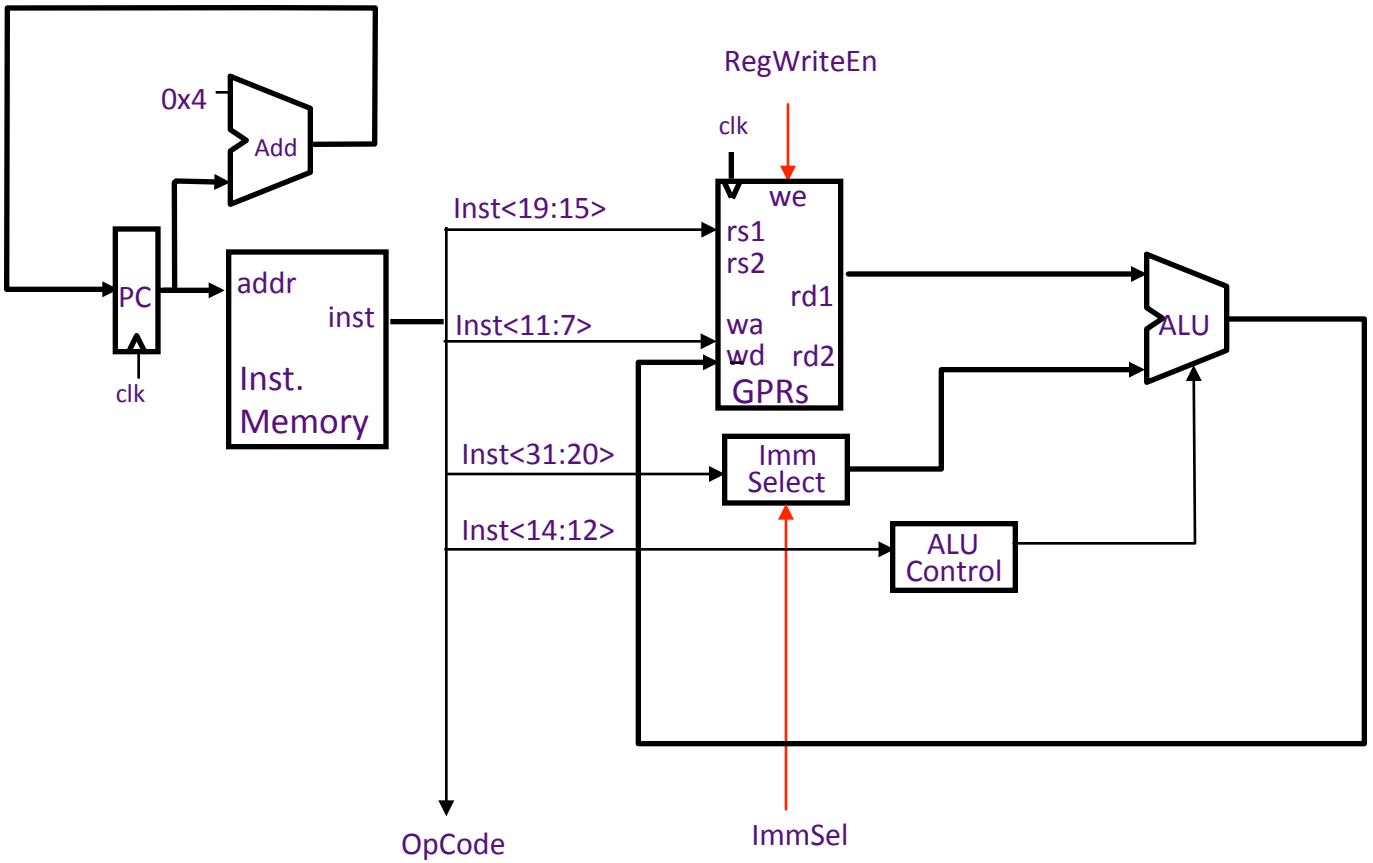


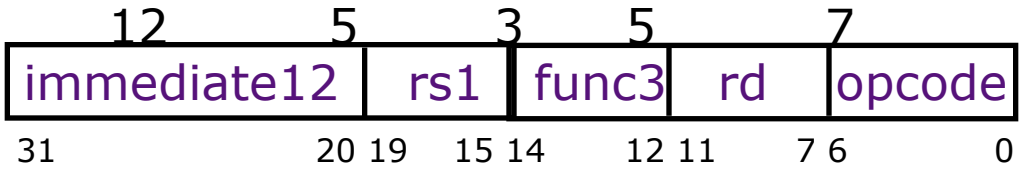
RegWrite Timing?



rd ← (rs1) func (rs2)

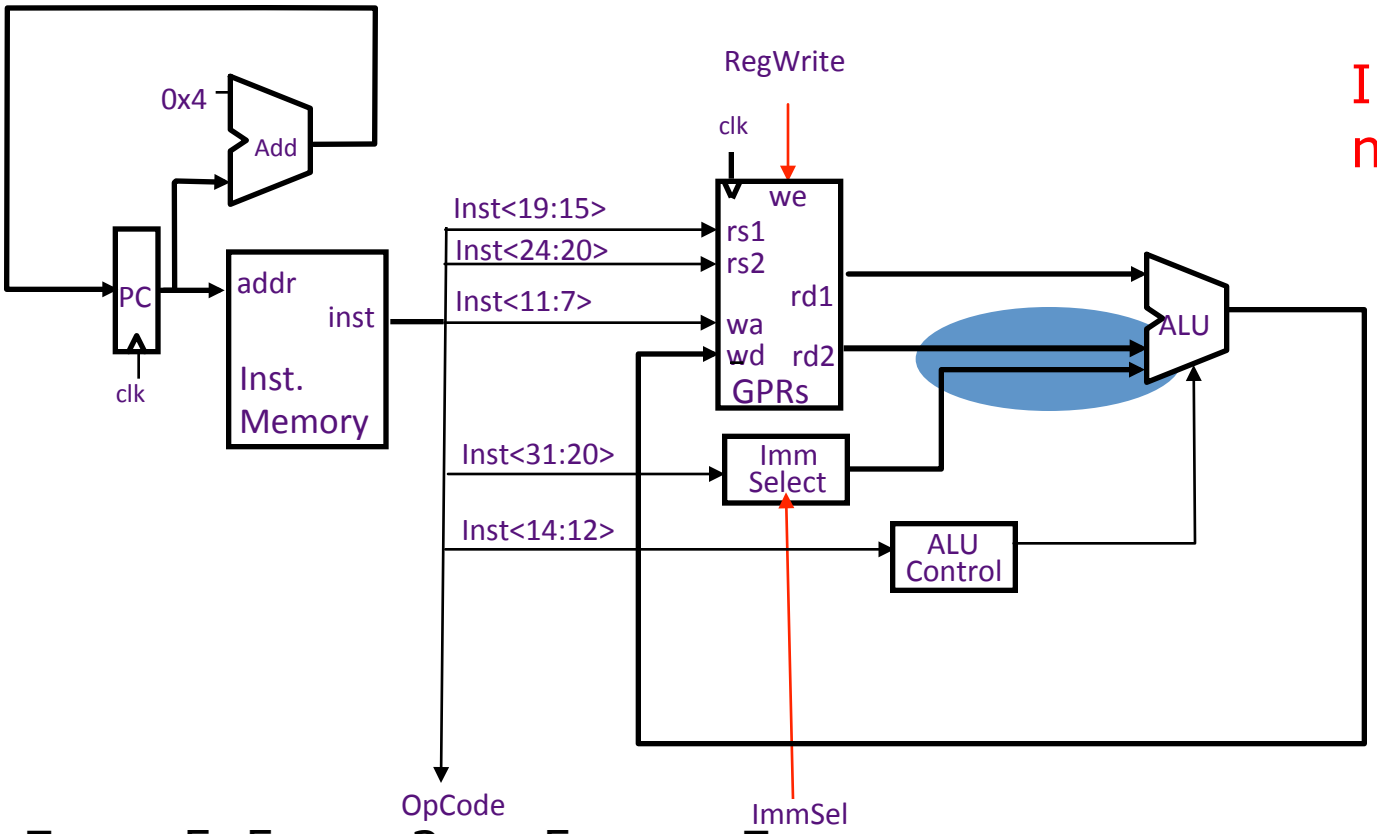
Datapath: Reg-Imm ALU Instructions



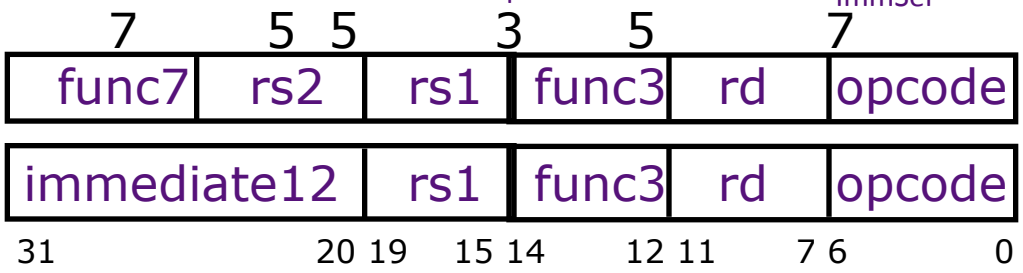


rd ← (rs1) op immediate

Conflicts in Merging Datapath



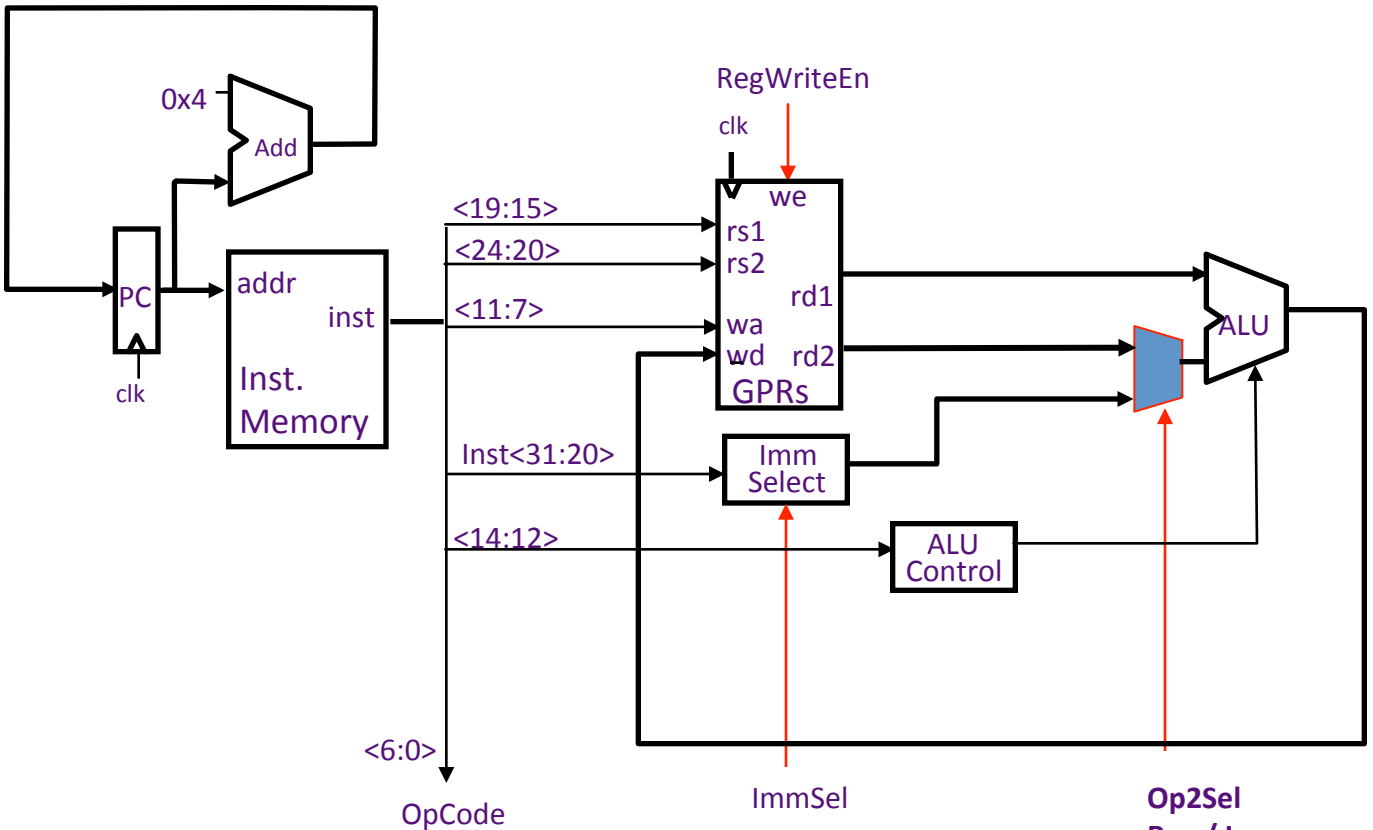
Introduce muxes

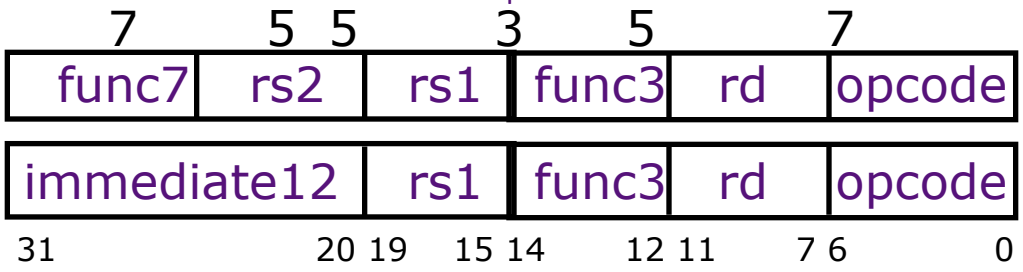


rd ← (rs1) func (rs2)

rd ← (rs1) op immediate

Datapath for ALU Instructions

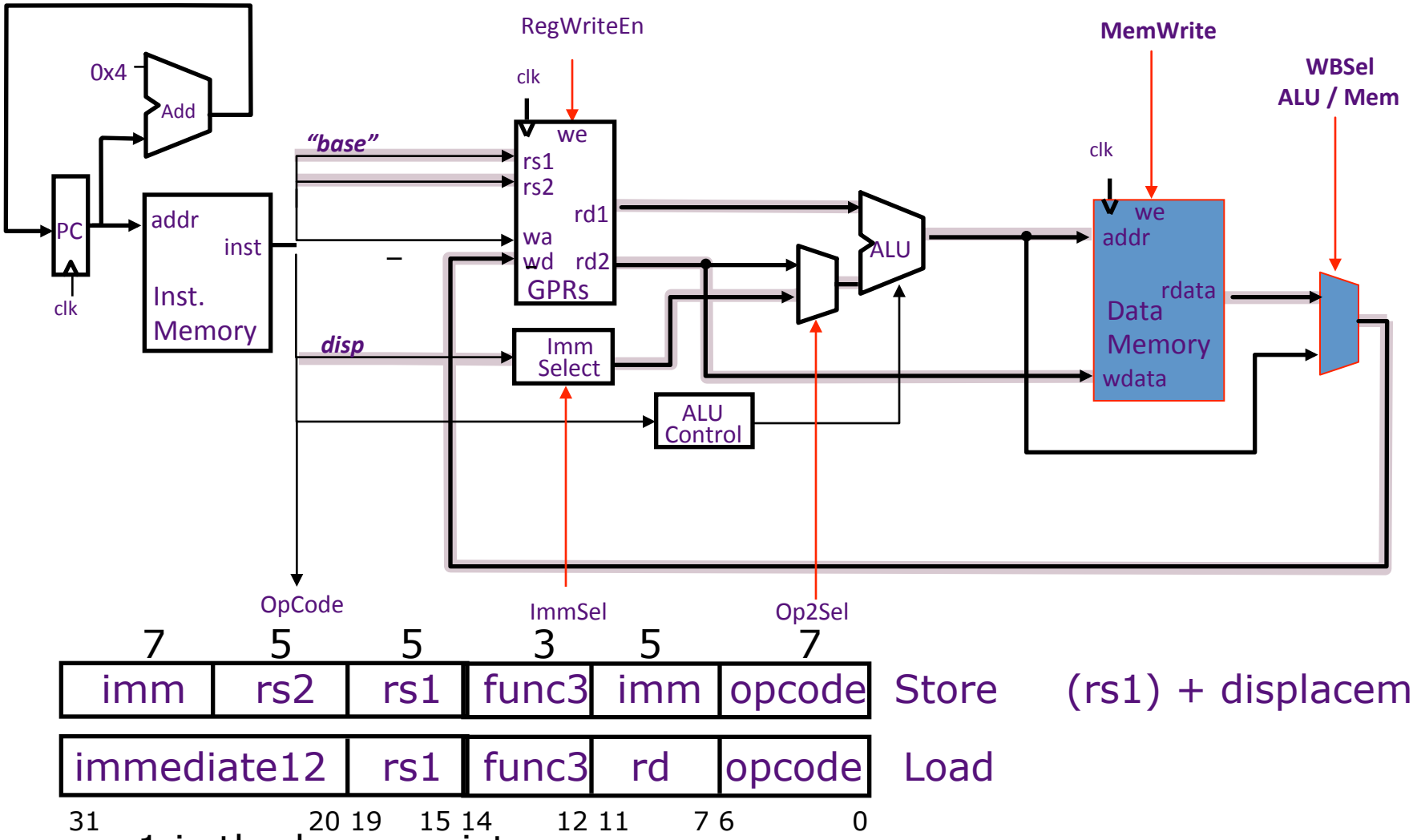




rd ← (rs1) func (rs2)

rd ← (rs1) op immediate

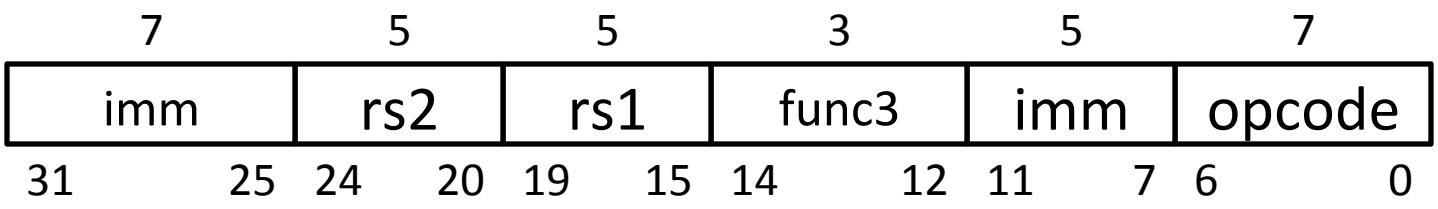
Load/Store Instructions



rs1 is the base register

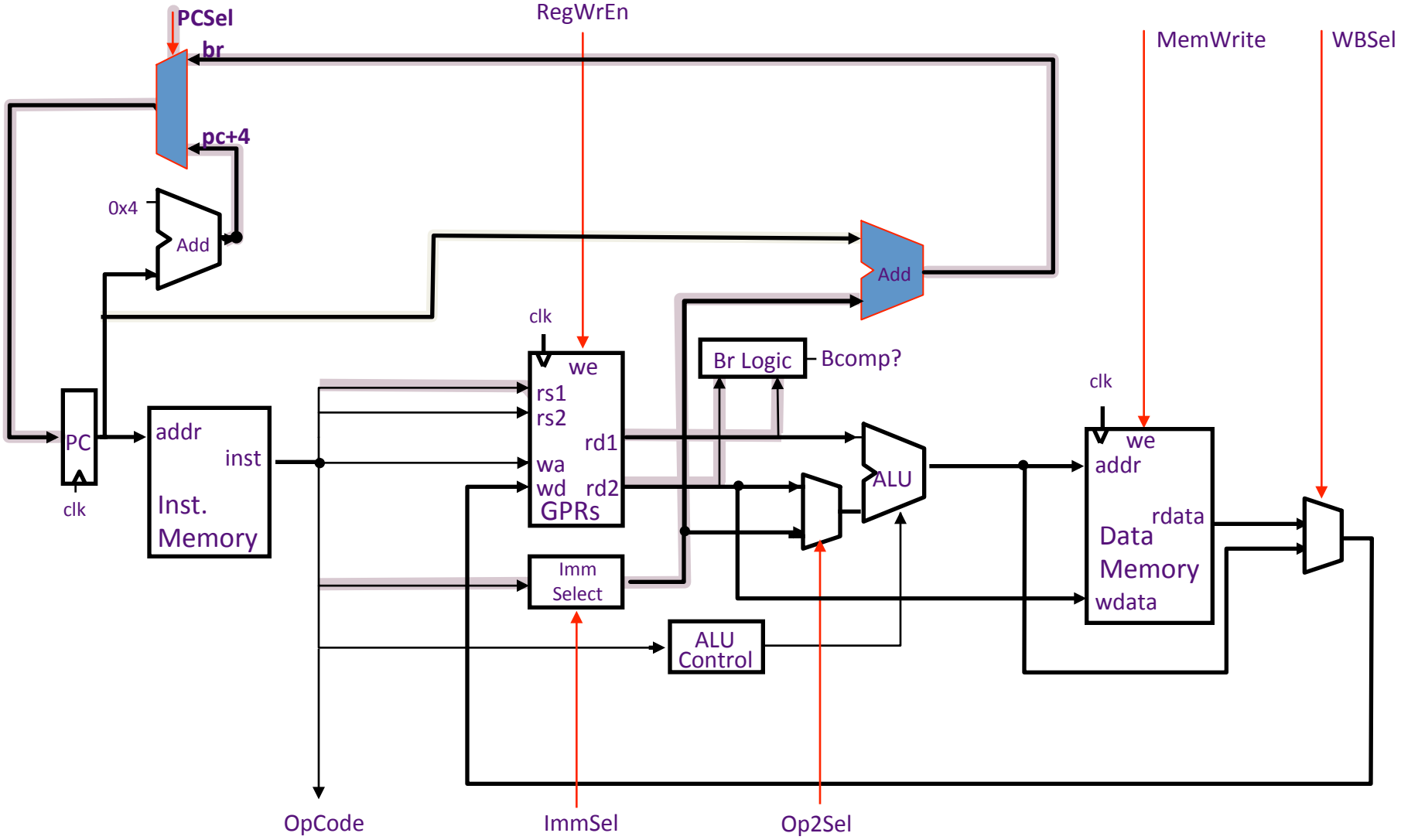
rd is the destination of a Load, rs2 is the data source for a Store

RISC-V Conditional Branches

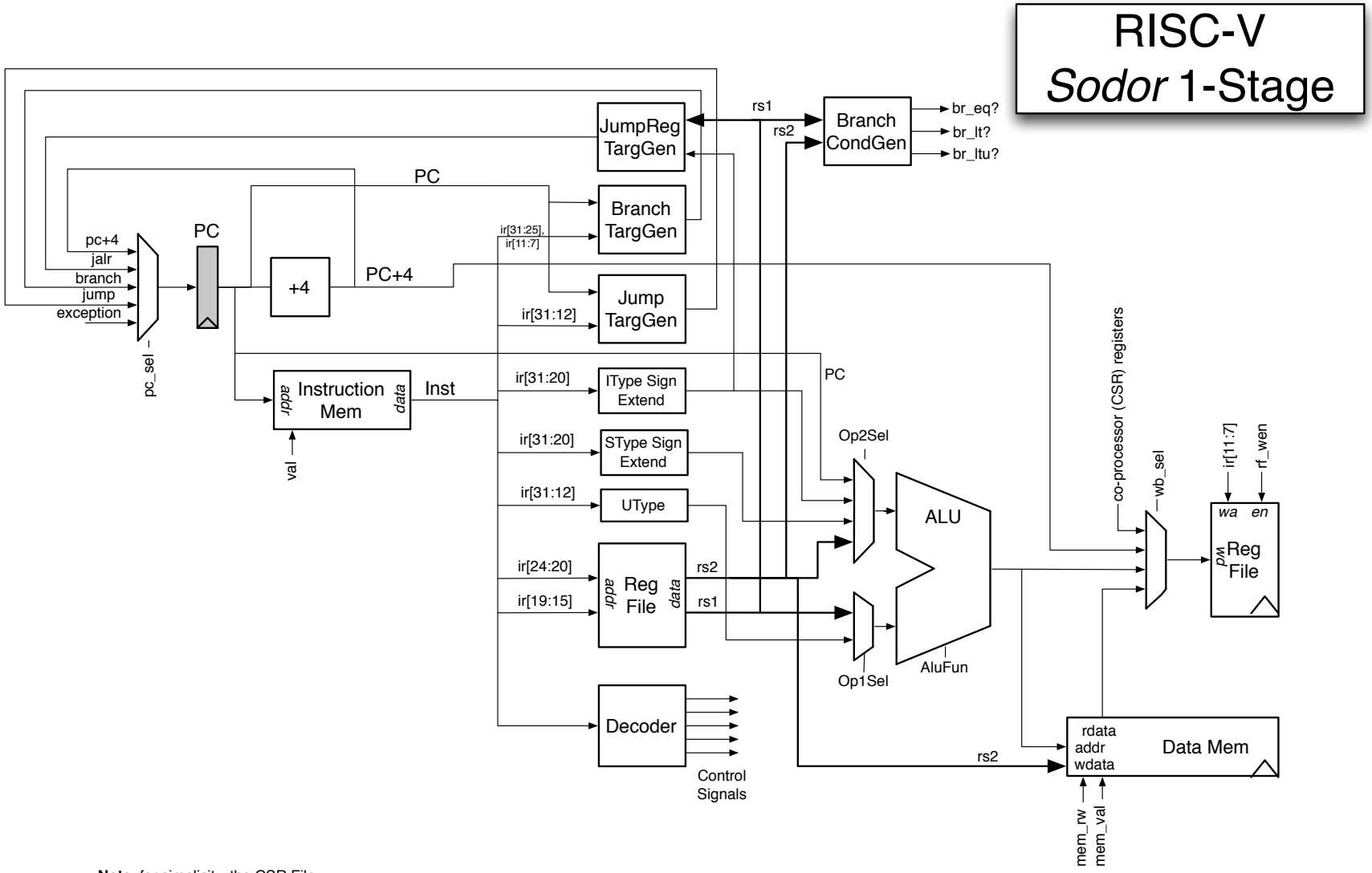


- Compare two integer registers for equality (BEQ/BNE) or signed magnitude (BLT/BGE) or unsigned magnitude (BLTU/BGEU)
- 12-bit immediate encodes branch target address as a signed offset from PC, in units of 16-bits (i.e., shift left by 1 then add to PC).

Conditional Branches (BEQ/BNE/BLT/BGE/BLTU/BGEU)



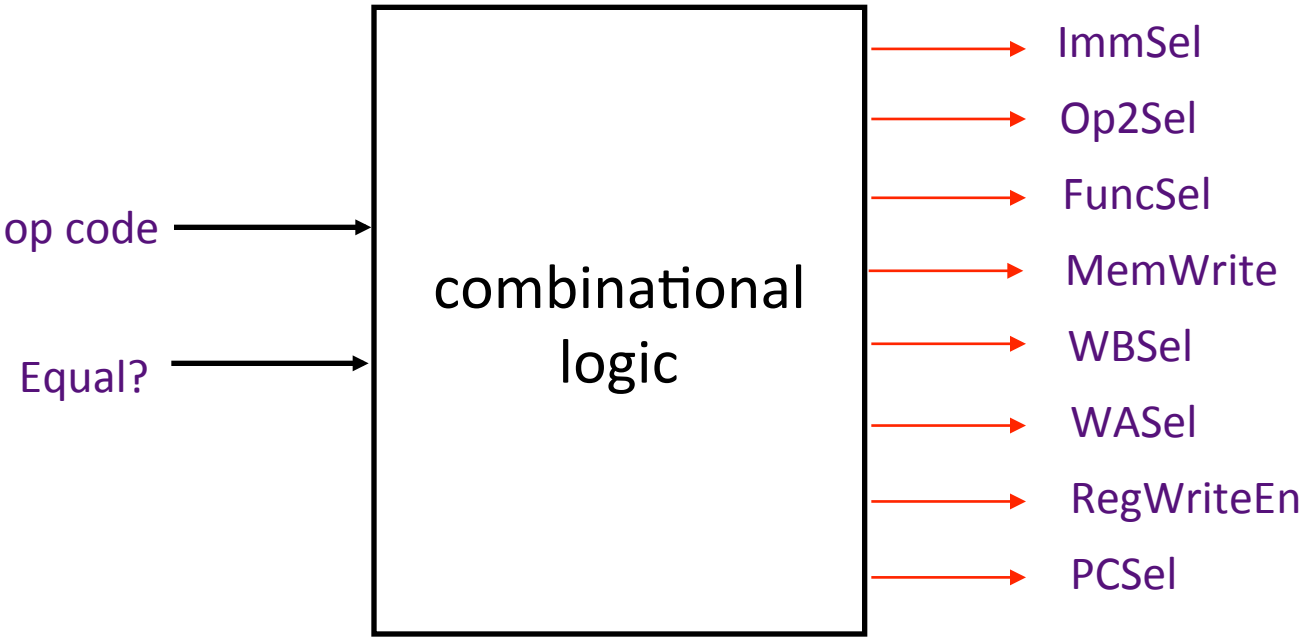
Full RISCV1Stage Datapath



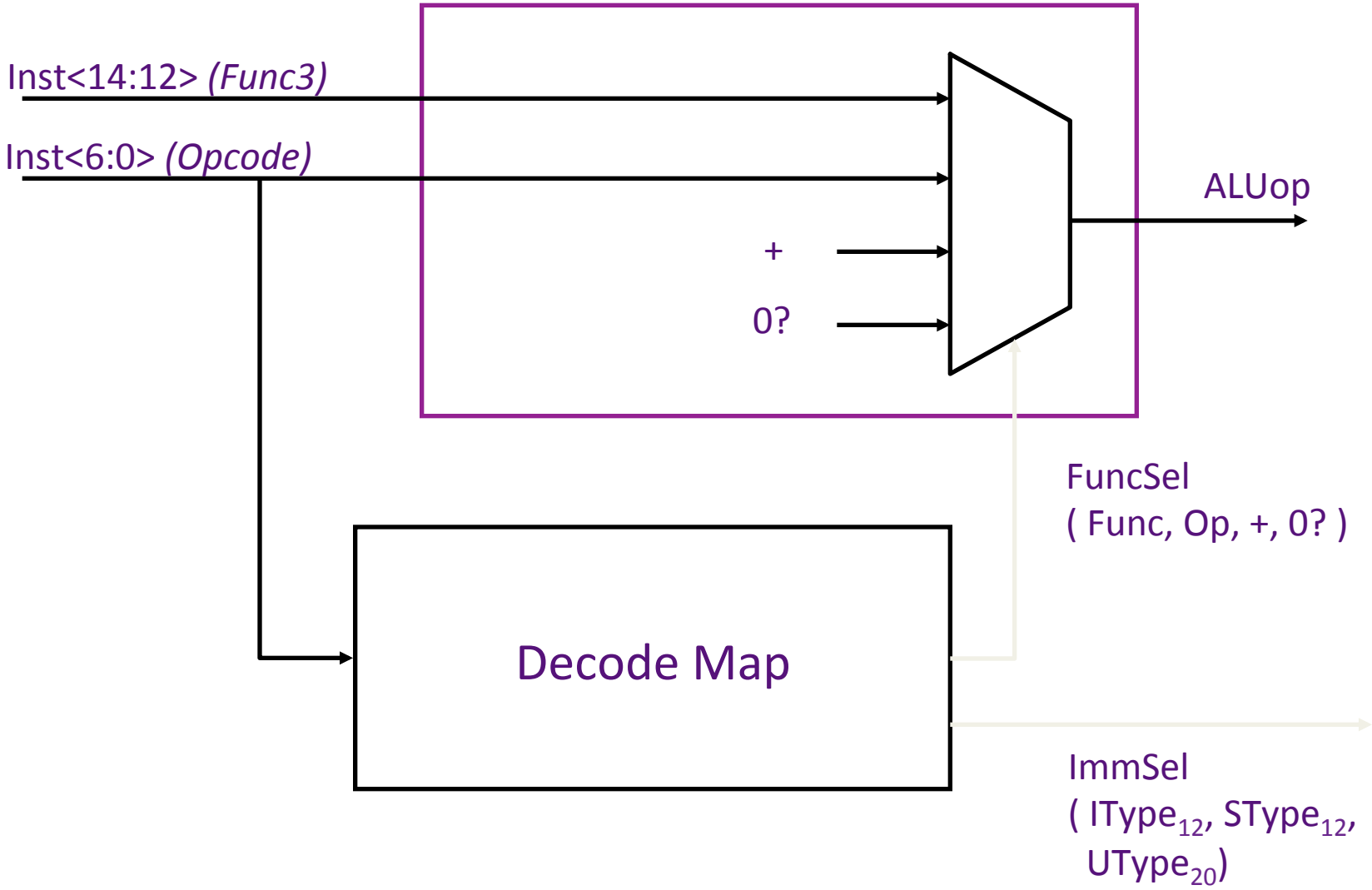
Note: for simplicity, the CSR File (control and status registers) and associated datapath is not shown

Execute Stage

Hardwired Control is pure Combinational Logic



ALU Control & Immediate Extension



Hardwired Control Table

Opcode	ImmSel	Op2Sel	FuncSel	MemWr	RFWen	WBSel	WASel	PCSel
ALU	*	Reg	Func	no	yes	ALU	rd	pc+4
ALUi	$IType_{12}$	Imm	Op	no	yes	ALU	rd	pc+4
LW	$IType_{12}$	Imm	+	no	yes	Mem	rd	pc+4
SW	$SType_{12}$	Imm	+	yes	no	*	*	pc+4
BEQ_{true}	$SBType_{12}$	*	*	no	no	*	*	br
BEQ_{false}	$SBType_{12}$	*	*	no	no	*	*	pc+4
J	*	*	*	no	no	*	*	jabs
JAL	*	*	*	no	yes	PC	X1	jabs
JALR	*	*	*	no	yes	PC	rd	rind

Op2Sel= Reg / Imm
WASel = rd / X1

WBSel = ALU / Mem / PC
PCSel = pc+4 / br / rind / jabs

Single-Cycle Hardwired Control

clock period is sufficiently long for all of the following steps to be "completed":

1. Instruction fetch
2. Decode and register fetch
3. ALU operation
4. Data fetch if required
5. Register write-back setup time

=> tC > tIFetch + tRFetch + tALU+ tDMem+ tRWB

At the rising edge of the following clock, the PC, register file and memory are updated

Implementation in Real

- Load-Store RISC ISAs designed for efficient pipelined implementations
  - Inspired by earlier Cray machines (CDC 6600/7600)
- RISC-V ISA implemented using Chisel hardware construction language
  - Chisel: https://chisel.eecs.berkeley.edu/
  - Getting started:
    - https://chisel.eecs.berkeley.edu/2.2.0/getting-started.html
  - Check resource page for slides and other info

Chisel in one slides

- Module
- IO
- Wire
- Reg
- Mem

```
import Chisel._

class GCD extends Module {
  val io = new Bundle {
    val a  = UInt(INPUT,  16)
    val b  = UInt(INPUT,  16)
    val e  = Bool(INPUT)
    val z  = UInt(OUTPUT, 16)
    val v  = Bool(OUTPUT)
  }
  val x  = Reg(UInt())
  val y  = Reg(UInt())
  when   (x > y) { x := x - y }
  unless (x > y) { y := y - x }
  when (io.e) { x := io.a; y := io.b }
  io.z := x
  io.v := y === UInt(0)
} ...
```

UCB RISC-V Sodor

- https://github.com/ucb-bar/riscv-sodor
  - Single-cycle:
    - https://github.com/ucb-bar/riscv-sodor/tree/master/src/rv32_1stage